

Last time,

Strong and weak scaling.

- I had an error in my eq<sup>n</sup> for efficiency of weak scaling.

→ Corrected on pdf & webpage.

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This time

- Machine models
- Measurements → to find parameters
- Scaling limits (Fischer 2015)

→ Data structure design for scalability.

Translating our abstract scaling  
onto hardware.

⇒ PDE solvers.

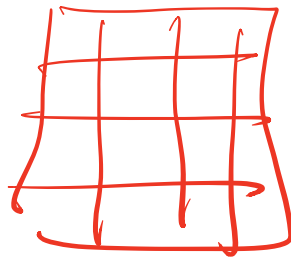
What are the scaling limits?

PDE I want to solve that has  
 $N$  total degrees of freedom

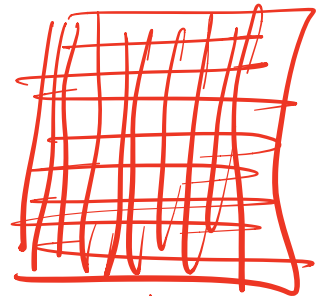
(dots)

↳ parameter that we can control  
by changing resolution.

I have a parallel  
computer available.



$N$  small



$N$  bigger

I can pick # processes  
 $P$  as big as I want.

If I can divide work ( $N$ ) by  
 $P$ , at what point should I stop?  
(When does the efficiency drop  
below 80%? 50%).

How small can I make  $\frac{N}{P}$   
without wasting too much  
resource?

Strong scaling problem:

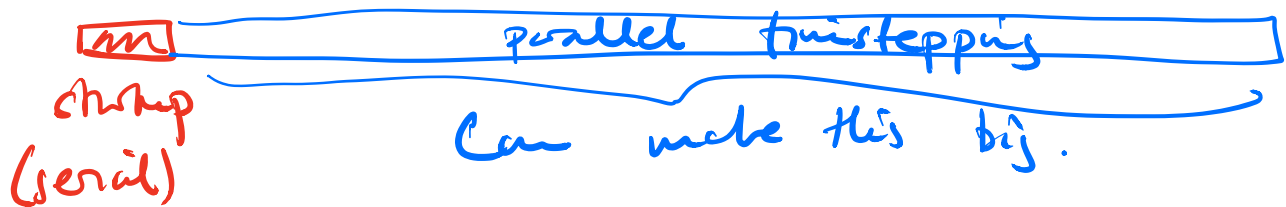
$N$  fixed &  $P$  varies.

Amdahl model:  $T_p = fT_1 + (1-f)\frac{T_1}{P}$

Where does this serial fraction  $f$  come from?

1. Unavoidably serial parts of our code. eg loading configuration, or printing summary data.

⇒ Typically can amortise this because for time-dep PDEs only need load config once



2. Communication takes time.

→ eg two processes have to exchange information every timestep.

say they need to exchange  $m$  bytes of data.

$$t(m) = \alpha + \beta m$$

$\downarrow$                        $\downarrow$   
 [s]                      [bytes]  
                             [s/byte].

non-dimensionalize  
 relevant timescale  $\tau$  has long it  
 takes to do some computational work.  
 → problem-specific

eg FD model, this time might be  
 "has long to update 1 point in the  
 grid".

$$u_{ij} \leftarrow -4u_{ij} + (u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1})$$

Call this  $t_f$

measure our code. → and find  
 eg # updates/s.

$$t(m) = \frac{\alpha}{t_f} + \frac{\beta}{t_f} m$$

hope hardware specs. ⇒ unfortunately not.

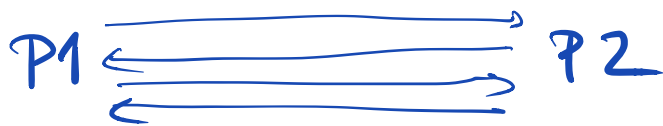
How long to send a message vs.  
 how long to do some compute?

$\alpha, \beta$ : need to know this for  
the parallel programming library  
we're using.

⇒ measure.

ping-pong measurements.

send message back and forth.



This should give nice clean data?

→ sometimes.

Let's and measure this.

Write some ping pong code

→ when uploaded

have a go doing these measurements  
for with & without numpy.